

## A Note on bias reduction using almost unbiased estimators of population mean in finite population sampling

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### ABSTRACT

In this paper we present a short review and discussion of some characterizations of almost unbiased ratio type estimators constructed at estimation stage. In such estimators the bias of  $O(1/n)$  is removed and the ultimate bias becomes of  $O(1/n^2)$ , where  $n$  is the sample size.

### KEYWORDS

Almost Unbiased estimators; Finite population; Ratio type estimators; Simple random sampling

## 1. Introduction

In large scale sample surveys to estimate the population mean/total of the study variable a researcher invariably collects information on some correlated auxiliary variables along with observations on the study variable. The reason is to construct an improved estimator compared to the mean per unit estimator of the study variable without use of auxiliary information. Ratio method of estimation is the most popular and simplest of all methods used in practice. However, the classical ratio estimator (Cochran,1940) is a biased estimator, although the bias becomes negligible for large samples. For small sample sizes the bias may be substantial, more so in stratification with ratio method of estimation in each stratum when the accumulated bias of the estimator makes the estimator unacceptable to be of any practical use (Cochran,1977). This discerning picture of classical ratio estimator has aroused continuing interest among many research workers during last seven decades to construct unbiased or almost unbiased ratio type estimators. In this paper we present some characterizations of classes of almost unbiased ratio type estimators constructed at estimation stage to be used in practice. In such estimators the bias of  $O(1/n)$  is removed and the ultimate bias becomes of  $O(1/n^2)$ , where  $n$  is the sample size.

## 2. Preliminaries

Consider a finite population  $U = \{U_1, U_2, \dots, U_N\}$  of size  $N$  distinct and identifiable units indexed by the values of characteristic  $y$  (study variable) and  $x$  (auxiliary variable)  $\{Y_i, X_i\}, i = 1, 2, \dots, N$ .

Select a simple random sample without replacement  $u = \{u_1, u_2, \dots, u_n\}$  of size  $n$  and the observed values of characteristics on the sample units are  $\{y_i, x_i\}, i = 1, 2, \dots, n$ .

Let  $\bar{Y}$  and  $\bar{X}$  be the population means of  $y$  and  $x$  respectively. Let  $S_y^2, S_x^2$  and  $S_{xy}$  be finite population variance of  $y$ , finite population variance  $x$  and finite population co-variance between  $x$  and  $y$  respectively.

$C_y = \frac{S_y}{\bar{Y}}$  coefficient of variation of  $y$ ,  $C_x = \frac{S_x}{\bar{X}}$  coefficient of variation of  $x$

$C_{xy} = \frac{S_{xy}}{\bar{Y}\bar{X}} = \rho C_x C_y$ ,  $\rho$  being the correlation coefficient between  $x$  and  $y$

$R = \frac{\bar{Y}}{\bar{X}}$

Define  $\bar{y}, \bar{x}, s_y^2, s_x^2$  and  $s_{xy}$  as sample mean of  $y$ , sample mean of  $x$ , sample variance of  $y$ , sample variance of  $x$  and sample co-variance between  $x$  and  $y$  respectively. Define

$c_y = \frac{s_y}{\bar{y}}, c_x = \frac{s_x}{\bar{x}}, c_{xy} = \frac{s_{xy}}{\bar{x}\bar{y}}, r = \frac{\bar{y}}{\bar{x}}$ . Put  $\theta = (\frac{1}{n} - \frac{1}{N})$

## 3. Formulation of a class of Almost unbiased Ratio estimators

The ratio estimator of the population ratio  $R = \frac{\bar{Y}}{\bar{X}}$ , given by  $r = \frac{\bar{y}}{\bar{x}}$  is a biased estimator having first order bias,  $\text{Bias}(r) = R\theta(C_x^2 - C_{xy})$ , (Sukhatme, et al., 1984), being of  $O(\frac{1}{n})$ , which may be negligible for large samples and tends to zero as  $n \rightarrow \infty$ . For small samples the bias may be substantial so as to make the estimator unacceptable to be used in practice. Cochran (1977) has shown that if the coefficient of variation of  $x$  is less than 0.1, then the bias of the simple ratio estimator is small relative to standard error.

Koop (1951), Quenouille (1956), Beale (1962) and Tin (1965) suggested improved ratio type estimators, whose first order bias is removed and the ultimate bias becomes of  $O(\frac{1}{n^2})$ , Tin (1965) has showed that to  $O(\frac{1}{n^2})$  Beale's estimator is less biased and has equal variance to that of his estimator and in large samples there is marginal loss of efficiency. His Monte Carlo simulations indicate better performances of Beale's estimator compared to Tin's and Quenouille's estimators. Hutchison (1971) compared Quenouille's, Beale's and Tin's estimators by Monte Carlo simulations and concluded that Beale's and Tin's estimators happened to be more efficient than Quenouille's under certain models. Beale's ratio estimator has been fruitfully applied to hydrological studies with least bias (Richards and Holloway, 1987; Richards, 1987).

Chakrabarty (1979) and Mussa (1999) suggested bias-reducing composite estimators involving simple expansion estimator and almost unbiased ratio estimators such as those of Quenouille's and Tin's estimators. Lui (2020) discussed the use of composite estimator simple mean estimator and ratio estimator with optimal weights to reduce the variance/mean square error of the ratio estimator. The bias and mean square error of composite estimators (with estimated optimal weight and known optimal weight) were examined both by Monte Carlo simulations and with applications to natural populations.

S. Singh and R. Singh (1993) devised a novel technique to arrive at a weighted combination of biased estimators, which is almost unbiased having variance equal to the large sample variance of the linear regression estimator.

### 3.1. A generalized class of almost unbiased ratio estimators

Swain(2015) suggested a generalized class of almost unbiased ratio estimators for Srivastava's(1971) class of ratio estimators

$$t_g = \bar{y}H(u)$$

under certain regularity conditions, where  $u = \bar{x}/\bar{X}$ . The suggested class of almost unbiased ratio estimators were

$$t_{gB} = t_g \frac{(1 - \theta H_1 \hat{C}_{yx})}{(1 + \theta H_2 \hat{C}_x^2)} \quad (\text{Beale type})$$

$$t_{gT} = t_g \left[ 1 - \theta \left( H_2 \hat{C}_x^2 + H_1 \hat{C}_{yx} \right) \right] \quad (\text{Tin type})$$

$$t_{gK} = \frac{t_g}{\left( 1 + \theta \left( H_2 \hat{C}_x^2 + H_1 \hat{C}_{yx} \right) \right)} \quad (\text{Koop type})$$

where  $\hat{C}_x^2 = \frac{s_x^2}{\bar{x}^2}$  and  $\hat{C}_{yx} = \frac{s_{yx}}{\bar{y}\bar{x}}$ ; where  $H_1 = \left( \frac{\partial H}{\partial u} \right)_{u=1}$  and  $H_2 = \frac{1}{2} \left( \frac{\partial^2 H}{\partial u^2} \right)_{u=1}$  are known constants.

The biases of  $t_{gB}$ ,  $t_{gT}$  and  $t_{gK}$  are of  $O(\frac{1}{n^2})$  first order biases being removed. To  $O(\frac{1}{n^2})$ , they have the same asymptotic variance.

Thus, we have the following theorem:

#### Theorem 1

The class of estimators  $\bar{y}H(u)$ , where  $u = \bar{x}/\bar{X}$  generates a class of almost unbiased estimators of the population mean  $\bar{Y}$  of the study variable  $y$ ,  $x$  being the auxiliary variable, if  $H(u)$  satisfies the regularity conditions:

- (1)  $H(1)=1$
- (2)  $H(u)$  continuous and bounded. The first and second derivatives of  $H$  with respect to  $u$  exists and are known constants at a given point  $u = 1$  at  $|u - 1| < 1$ .
- (3)  $H(u)$  is expandable under Taylor's series expansion subject to the required regularity conditions as:

$$\begin{aligned} H(u) &= H(1 + (u - 1)) \\ &= H(1) + (u - 1) \left( \frac{\partial H}{\partial u} \right)_{u=1} + (u - 1)^2 \frac{1}{2} \left( \frac{\partial^2 H}{\partial u^2} \right)_{u=2} + \dots \end{aligned}$$

The application of the above theorem gives

$$\bar{y}H(u) = Y \left( H(1) + \theta H_2 C_x^2 + \theta H_1 C_{yx} + O(1/n^2) \right)$$

where  $H_1 = \left( \frac{\partial H}{\partial u} \right)_{u=1}$  and  $H_2 = \frac{1}{2} \left( \frac{\partial^2 H}{\partial u^2} \right)_{u=1}$

The first order bias is Bias =  $\bar{Y} \left( \theta H_2 C_x^2 + \theta H_1 C_{yx} \right)$

Thus we can construct Beale's estimator as  $t_B = \bar{y} \frac{\bar{X}}{\bar{x}} \left[ \frac{1 - \theta H_1 C_{yx}}{(1 + \theta H_2 C_x^2)} \right]$

And Tin's estimator as  $t_T = \bar{y} \frac{\bar{X}}{\bar{x}} [1 - \theta (H_1 C_{yx} + H_2 C_x^2)]$

Koop's estimator as  $t_K = \bar{y} \frac{\bar{X}}{\bar{x}} [1 + \theta (H_1 C_{yx} + H_2 C_x^2)]^{-1}$

Depending on the functional form of  $H(u)$ , the values of  $H_1$  and  $H_2$  will vary.

### 3.2. An alternative class of almost unbiased ratio estimators

In the following we derive an alternative simple method for the characterization of a class of almost unbiased estimators with less restrictive assumptions.

Define the generalized ratio estimator as

$$r_g = \frac{\bar{y} + \theta a}{\bar{x} + \theta b} \quad (1)$$

where  $a$  and  $b$  may be either real constants or random variables converging in probability to constants.

Let  $\bar{y} = \bar{Y} (1 + e_0)$  and  $\bar{x} = \bar{X} (1 + e_1)$ ,

$$E(e_0) = E(e_1) = 0 \text{ and } V(e_0) = \theta C_y^2, V(e_1) = \theta C_x^2$$

$$Cov(e_0, e_1) = \theta C_{yx}.$$

Now expanding  $r_g$  in a binomial series with assumption  $|e_1 + \frac{\theta}{\bar{X}}| < 1$  for all  $C_n^N$  possible samples, and retaining terms up to and including degree two in  $e_0$  and  $e_1$ , we have

$$\begin{aligned} r_g = R [ & 1 - \frac{\theta b}{\bar{X}} + e_1^2 + \frac{\theta^2 b^2}{\bar{X}^2} - 2e_1 \frac{\theta b}{\bar{X}} - e_0 e_1 + e_0 (e_1^2 + \frac{\theta^2 b^2}{\bar{X}^2} - 2e_1 \frac{\theta b}{\bar{X}}) + \frac{\theta a}{\bar{Y}} - \frac{\theta^2 ab}{\bar{Y} \bar{X}} \\ & + \frac{\theta a}{\bar{Y}} (e_1^2 + \frac{\theta^2 b^2}{\bar{X}^2} - 2e_1 \frac{\theta b}{\bar{X}}) ] \end{aligned} \quad (2)$$

Taking expectation of  $r_g$  and keeping terms up to  $O(1/n)$ , we have

$$E(r_g) = R \left[ 1 - \frac{\theta b}{\bar{X}} + \theta C_x^2 - \theta C_{yx} + \frac{\theta a}{\bar{Y}} \right] \quad (3)$$

$$Bias(r_g) = E(r_g) - R \quad (4)$$

In order that the first order bias is zero we put,

$$\frac{\theta a}{\bar{Y}} - \frac{\theta b}{\bar{X}} = \theta (C_{yx} - C_x^2) \quad (5)$$

or

$$\frac{a}{\bar{Y}} - \frac{b}{\bar{X}} = (C_{yx} - C_x^2)$$

For a chosen value of  $b$  or  $a$  we get a value for  $a$  or  $b$ .  
Hence we may state the following theorem.

**Theorem 2**

The necessary and sufficient condition for  $r_g$  to be almost unbiased for  $\mathbf{R}$  is

$$\frac{a}{\bar{Y}} - \frac{b}{\bar{X}} = (C_{yx} - C_x^2)$$

Case I Put  $b = \bar{X}C_x^2$

Thus, we have  $\frac{a}{\bar{Y}} = (C_{yx} - C_x^2) + \frac{b}{\bar{X}} = (C_{yx} - C_x^2) + \frac{\bar{X}C_x^2}{\bar{X}} = C_{yx}$ ,

which simplifies to  $a = \bar{Y}C_{yx} = \frac{S_{yx}}{\bar{X}}$

$a$  and  $b$  are functions of unknown population parameters which are usually unknown. These may be replaced by the corresponding design consistent estimates, which does not affect order of approximations. Thus,  $\hat{a} = \frac{s_{yx}}{\bar{x}}$  and  $\hat{b} = \frac{s_x^2}{\bar{x}}$ .

After substitution of  $\hat{a}$  and  $\hat{b}$ , in place of  $a$  and  $b$ ,  $r_g$  is rewritten as

$r_{gB} = \frac{\bar{y} + \theta s_{yx}/\bar{x}}{\bar{x} + \theta s_x^2/\bar{x}} = r \left[ \frac{1 + \theta c_{yx}}{1 + \theta c_x^2} \right]$ , which is  $r_B$ , an almost unbiased ratio type estimator proposed by Beale (1962).

Case II Put  $b = 0$ , then  $\frac{a}{\bar{Y}} = (C_{yx} - C_x^2)$

The design consistent estimator  $\hat{a} = y(c_{yx} - c_x^2)$

Hence  $r_G$  is rewritten as

$r_{gT} = r [1 + \theta (c_{yx} - c_x^2)] = r_T$ , which was proposed by Tin (1965).

Case III Put  $a = 0$ , then

$$b = \bar{X}C_x^2 - \bar{X}C_{yx}.$$

The design consistent estimator  $\hat{b} = \bar{x}c_x^2 - \bar{x}c_{yx}$

Then  $r_g$  is rewritten as

$$r_{gk} = \frac{r}{\left[ 1 + \theta \left( \frac{s_x^2}{\bar{x}^2} - \frac{s_{yx}}{\bar{y}\bar{x}} \right) \right]} = \frac{r}{[1 + \theta (c_x^2 - c_{yx})]} = r_k$$

which was suggested by Koop (1951) by dividing the estimator by the estimate of its bias component.

Thus we see that we can generate large class of almost unbiased ratio estimator by suitable choice of either  $a$  or  $b$ .

**4. Generalized almost unbiased (Linear variety) separation of bias precipitates method( Singh-Singh,1993)**

Construct an estimator as

$$t = w_1t_1 + w_2t_2 + w_3t_3$$

$$w_1 + w_2 + w_3 = 1 \quad (6)$$

$$t_1 = \bar{y}, t_2 = \bar{y}H(u), t_3 = \bar{y}G(u)$$

$H(u)$  and  $G(u)$  are continuous bounded functions of  $u = \bar{x}/\bar{X}$ , and  $H(u)$  and  $G(u)$  are not equivalent and satisfy following assumptions

- (1)  $H(1) = 1, G(1) = 1$ .
- (2) First and second derivatives of  $H(u)$  and  $G(u)$  exist.

Writing  $H(u) = H(1 + u - 1)$ ,  $G(u) = G(1 + u - 1)$  and expanding  $H(u)$  and  $G(u)$  in Taylor's series at the point  $u = 1$  with  $|u - 1| < 1$ , we have

$$\begin{aligned} H(u) &= H(1) + (u-1)H'(u)_{u=1} + \frac{1}{2}(u-1)^2H''(u)_{u=1} + \dots \\ G(u) &= G(1) + (u-1)G'(u)_{u=1} + \frac{1}{2}(u-1)^2G''(u)_{u=1} + \dots \end{aligned}$$

where  $H'(u)$  and  $G'(u)$  are first derivatives of  $H(u)$  and  $G(u)$  respectively,  $H''(u)$  and  $G''(u)$  are second derivatives respectively.

Writing  $H'(u)_{u=1} = H_1$  and  $\frac{1}{2}H''(u)_{u=1} = H_2$   
 $G'(u)_{u=1} = G_1$  and  $\frac{1}{2}G''(u)_{u=1} = G_2$ ,  
 we have

$$\begin{aligned} H(u) &= 1 + (u-1)H_1 + \frac{1}{2}(u-1)^2H_2 + \dots \\ G(u) &= 1 + (u-1)G_1 + \frac{1}{2}(u-1)^2G_2 + \dots \end{aligned}$$

Defining  $e_0 = \frac{\bar{y}}{\bar{Y}} - 1$  and  $e_1 = u - 1$ . we write

$$\begin{aligned} E(t) &= w_1E(t_1) + w_2E(t_2) + w_3E(t_3) \\ &= E[w_1\bar{Y}(1+e_0) + w_2\bar{Y}(1+e_0)(1+e_1H_1 + e_1^2H_2 + \dots) \\ &\quad + w_3\bar{Y}(1+e_0)(1+e_1G_1 + e_1^2G_2 + \dots)] \end{aligned}$$

$$Bias(t) = w_2\bar{Y}\theta [H_2C_x^2 + H_1C_{xy}] + w_3\bar{Y}\theta [G_2C_x^2 + G_1C_{xy}]$$

Substituting the bias of  $t$  to  $O(1/n)$  equal to zero, we have

$$w_2 [H_2C_x^2 + H_1C_{xy}] + w_3 [G_2C_x^2 + G_1C_{xy}] = 0 \quad (7)$$

For optimum variance of  $t$  to  $O(1/n)$  we require

$$w_2H_1 + w_3G_1 = -\rho \frac{C_y}{C_x} = -k, \text{ say} \quad (8)$$

where

$$k = \rho \frac{C_y}{C_x}$$

We now put the equations (6), (7) and (8) in the following matrix form to solve for the weights  $w_1, w_2$  and  $w_3$  and hence the almost unbiased ratio type estimator  $t$ , whose bias is of  $O(1/n)$  and the asymptotic variance is equal to that of the linear regression estimator.

$$\begin{bmatrix} 0 & H_1 & G_1 \\ 1 & 1 & 1 \\ 0 & B_2 & B_3 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} -k \\ 1 \\ 0 \end{bmatrix} \quad (9)$$

where  $B_2 = B(t_2) = \theta(H_2C_x^2 + H_1C_{xy})$  and  $B_3 = B(t_3) = \theta(G_2C_x^2 + G_1C_{xy})$

The solutions of  $w_1, w_2$  and  $w_3$  are

$w_1 = \Delta_1/\Delta$ ,  $w_2 = \Delta_2/\Delta$  and  $w_3 = \Delta_3/\Delta$ , where

$\Delta_1 = -kB_3 + kB_2 + G_1B_2 - H_1B_3$ ,  $\Delta_2 = kB_3$ ,  $\Delta_3 = -kB_2$  and  $\Delta = G_1B_2 - H_1B_3$ .

It may be verified,

$$\begin{aligned} Bias(t) &= (\Delta_2/\Delta)(H_2C_x^2 + H_1C_{xy}) + \Delta_3/\Delta(G_2C_x^2 + G_1C_{xy}) \\ &= \frac{k(G_2C_x^2 + G_1C_{xy})}{G_1(H_2C_x^2 + H_1C_{xy}) - H_1(G_2C_x^2 + G_1C_{xy})} (H_2C_x^2 + H_1C_{xy}) \\ &\quad - \frac{k(H_2C_x^2 + H_1C_{xy})}{G_1(H_2C_x^2 + H_1C_{xy}) - H_1(G_2C_x^2 + G_1C_{xy})} (G_2C_x^2 + G_1C_{xy}) = 0 \end{aligned} \quad (10)$$

As  $t$  happens to be functions of unknown population parameters  $C_x, C_y$  and  $\rho$ , these may be substituted by their design consistent estimates. The resulting asymptotic variance of the estimator after substituting the estimates of the unknown parameters is equal to the asymptotic variance of the linear regression estimator given by  $\theta\bar{Y}C_y^2(1 - \rho^2)$ .

Examples

$$H(u) = \left(\frac{\bar{X}}{\bar{x}}\right), G(u) = e^{-\frac{1}{2}(\bar{x} - \bar{X})\bar{X}}, H_1 = -1, G_1 = -\frac{1}{2}, H_2 = 1, G_2 = \frac{3}{8}$$

$$H(u) = \left(\frac{\bar{X}}{\bar{x}}\right)\alpha, G(u) = \frac{\bar{X}}{\alpha\bar{x} + (1-\alpha)\bar{X}}, H_1 = -\alpha, G_1 = -\alpha, H_2 = \alpha(\alpha + 1)/2, G_2 = \alpha^2.$$

We now state the following Theorem as follows

### Theorem 3

$$t_1 = \bar{y}, t_2 = \bar{y}H(u), t_3 = \bar{y}G(u)$$

where  $H(u)$  and  $G(u)$  are continuous and bounded functions, satisfying certain regularity functions stated above, then

$$t = w_1t_1 + w_2t_2 + w_3t_3$$

with  $w_1 + w_2 + w_3 = 1$ ,  $w_2 = \frac{k(G_2C_x^2 + G_1C_{xy})}{G_1(H_2C_x^2 + H_1C_{xy}) - H_1(G_2C_x^2 + G_1C_{xy})}$

$$\text{and } w_3 = -\frac{k(H_2C_x^2 + H_1C_{xy})}{G_1(H_2C_x^2 + H_1C_{xy}) - H_1(G_2C_x^2 + G_1C_{xy})}$$

where  $k = \rho \frac{C_y}{C_x}$ , is an almost unbiased estimator with first order bias  $O(1/n)$  removed and the variance of  $t$  being asymptotically equal to that of a linear regression estimator.

## 5. Conclusion

Two classes of generalized almost unbiased ratio type estimators are suggested, whose biases to  $O(1/n)$  are removed. The well known Beale and Tin type modified ratio estimators are derived as special cases. In latter case another generalized weighted class of almost unbiased ratio estimators are derived where the bias of  $O(1/n)$  is also removed and the asymptotic variance equals to that of the linear regression estimator. The suggested methods can also be applied to formulate almost unbiased ratio estimators for other finite population parametric functions.

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